

- **Complete PCM Codec and Filtering Systems Include:**
 - Transmit High-Pass and Low-Pass Filtering
 - Receive Low-Pass Filter With (sin x)/x Correction
 - Active RC Noise Filters
 - μ -Law and A-Law Compatible Coder and Decoder
 - Internal Precision Voltage Reference
 - Serial I/O Interface
 - Internal Autozero Circuitry
- μ -Law/A-Law Operation Pin-Selectable
- ± 5 -V Operation
- Low Operating Power . . . 60 mW Typ
- Power-Down Mode . . . 5 mW Typ
- Automatic Power Down
- TTL- or CMOS-Compatible Digital Interface
- Maximizes Line Interface Card Circuit Density

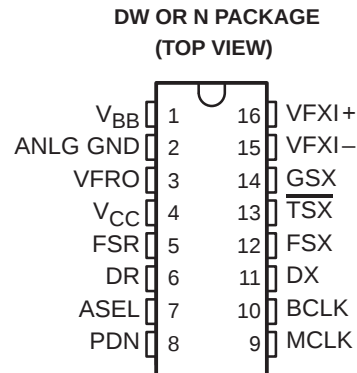
description

The TP3056B monolithic serial interface combined PCM codec and filter device is comprised of a single-chip PCM codec (pulse code-modulated encoder and decoder) and analog filters. This device provides all the functions required to interface a full-duplex (2-wire) voice telephone circuit with a TDM (time-division-multiplexed) system. Primary applications include:

- Line interface for digital transmission and switching of T1/E1 carrier, PABX, and central office telephone systems
- Subscriber line concentrators
- Digital-encryption systems
- Digital voice-band data-storage systems
- Digital signal processing

The TP3056B is designed to perform the transmit encoding (A/D conversion) and receive decoding (D/A conversion), and the appropriate filtering of analog signals in a PCM system. This device is intended to be used at the analog termination of a PCM line or trunk. It requires a master clock of 2.048 MHz, a transmit/receive data clock that is synchronous with the master clock (but can vary from 64 kHz to 2.048 MHz), and transmit and receive frame-sync pulses. The TP3056B contains patented circuitry to achieve low transmit channel idle noise and is not recommended for applications in which the composite signals on the transmit side are below -55 dBm0.

This device, available in 16-pin N PDIP (plastic dual-in-line package) and 16-pin DW SOIC (small outline IC) packages, is characterized for operation from 0°C to 70°C .



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

 **TEXAS
INSTRUMENTS**

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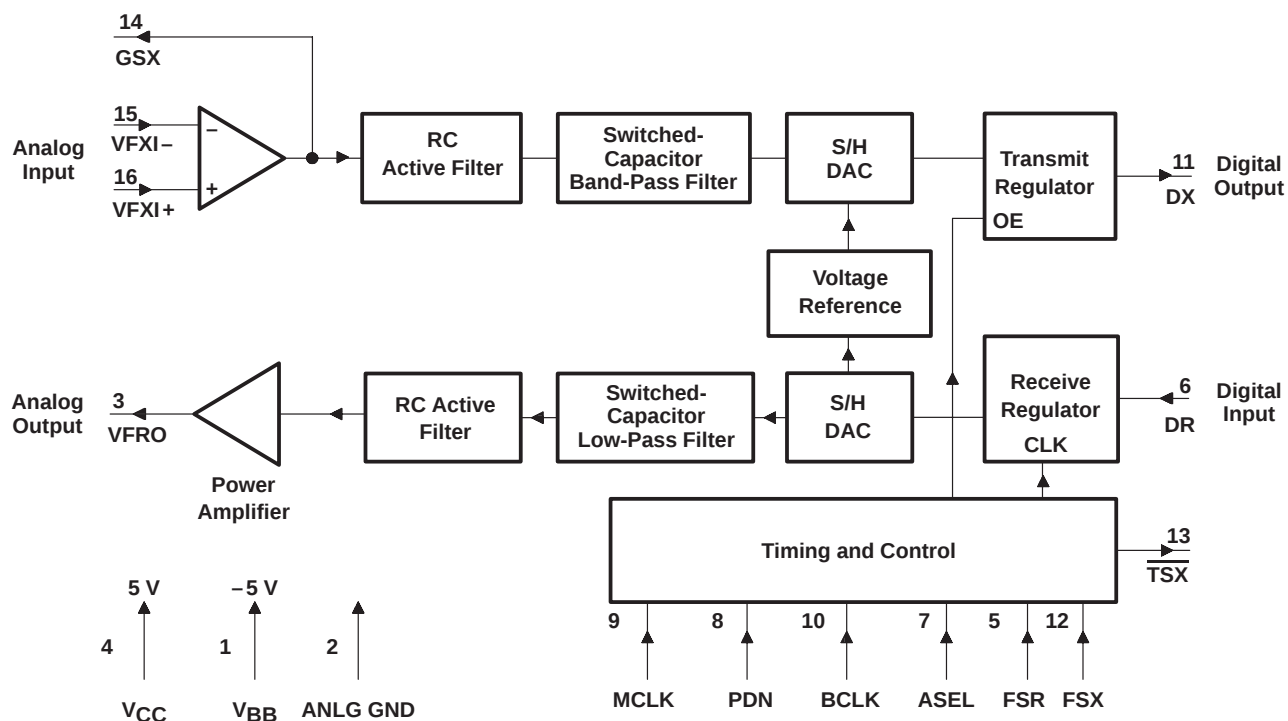
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MONOLITHIC SERIAL INTERFACE COMBINED PCM CODEC AND FILTER

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functional block diagram



Terminal Functions

TERMINAL NAME	NO.	I/O	DESCRIPTION
ANLG GND	2		Analog ground. All signals are referenced to ANLG GND.
ASEL	7	I	A-law/ μ -law select. When ASEL is connected to V_{CC} , A-law is selected. When ASEL is connected to GND or V_{BB} , μ -law is selected.
BCLK	10	I	Transmit/receive bit clock. BCLK shifts PCM data out on DX during transmit and shifts PCM data in through DR during receive. BCLK can vary from 64 kHz to 2.048 MHz, but must be synchronous with MCLK.
DR	6	I	Receive data input. PCM data is shifted into DR at the trailing edge of the BCLK following the FSR leading edge.
DX	11	O	DX is the 3-state PCM data output that is enabled by FSX. Data is shifted out on the rising edge of BCLK.
FSR	5	I	Receive-frame sync pulse input. FSR enables BCLK to shift PCM data in DR. FSR is an 8-kHz pulse train (see Figures 1 and 2 for timing details).
FSX	12	I	Transmit-frame sync pulse. FSX enables BCLK to shift out the PCM data on DX. FSX is an 8-kHz pulse train (see Figures 1 and 2 for timing details).
GSX	14	O	Analog output of the transmit input amplifier. GSX is used to set gain externally.
MCLK	9	I	Transmit/receive master clock. MCLK must be 2.048 MHz.
PDN	8	I	Power down. When PDN is connected high, the device is powered down. When PDN is connected low or left floating, the device is powered up. PDN is internally tied low.
$\overline{\text{TSX}}$	13	O	Transmit channel time-slot strobe. $\overline{\text{TSX}}$ is an open-drain output that pulses low during the encoder time slot.
V_{BB}	1		Negative power supply. $V_{BB} = -5\text{ V} \pm 5\%$
V_{CC}	4		Positive power supply. $V_{CC} = 5\text{ V} \pm 5\%$
VFRO	3	O	Analog output of the receive channel power amplifier
VFXI+	16	I	Noninverting input of the transmit input amplifier
VFXI–	15	I	Inverting input of the transmit input amplifier

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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)[†]

Supply voltage, V_{CC} (see Note 1)	7 V
Supply voltage, V_{BB} (see Note 1)	–7 V
Voltage range at any analog input or output	$V_{CC} + 0.3$ V to $V_{BB} - 0.3$ V
Voltage range at any digital input or output	$V_{CC} + 0.3$ V to ANLG GND – 0.3 V
Continuous total dissipation	See Dissipation Rating Table
Operating free-air temperature range: TP3056B	0°C to 70°C
Storage temperature range, T_{stg}	–65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds: DW or N package	260°C

[†] Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltages are with respect to GND.

DISSIPATION RATING TABLE

PACKAGE	$T_A \leq 25^\circ\text{C}$ POWER RATING	DERATING FACTOR ABOVE $T_A = 25^\circ\text{C}$	$T_A = 70^\circ\text{C}$ POWER RATING	$T_A = 85^\circ\text{C}$ POWER RATING
DW	1025 mW	8.2 mW/°C	656 mW	533 mW
N	1150 mW	9.2 mW/°C	736 mW	598 mW

recommended operating conditions (see Note 2)

	MIN	NOM	MAX	UNIT
Supply voltage, V_{CC}	4.75	5	5.25	V
Supply voltage, V_{BB}	–4.75	–5	–5.25	V
High-level input voltage, V_{IH}	2.2			V
Low-level input voltage, V_{IL}			0.6	V
Common-mode input voltage range, $V_{ICR}^{\ddagger}$			±2.5	V
Load resistance, GSX, R_L	10			kΩ
Load capacitance, GSX, C_L			50	pF
Operating free-air temperature, T_A	0		70	°C

[‡] Measured with CMRR > 60 dB

NOTE 2: To avoid possible damage to these CMOS devices and resulting reliability problems, the power-up procedure described in the device power-up sequence paragraphs later in this document should be followed.

electrical characteristics over recommended ranges of supply voltage operating free-air temperature range, in A-law and μ -law modes (unless otherwise noted)

supply current

PARAMETER		TEST CONDITIONS	TP3056B			UNIT
			MIN	TYP [§]	MAX	
I_{CC} Supply current from V_{CC}	Power down	No load		0.5	1	mA
	Operating			6	9	
I_{BB} Supply current from V_{BB}	Power down	No load		0.5	1	mA
	Operating			6	9	

[§] All typical values are at $V_{CC} = 5$ V, $V_{BB} = -5$ V, and $T_A = 25^\circ\text{C}$.



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electrical characteristics at $V_{CC} = 5\text{ V} \pm 5\%$, $V_{BB} = -5\text{ V} \pm 5\%$, GND at 0 V, $T_A = 25^\circ\text{C}$ (unless otherwise noted)

digital interface

PARAMETER			TEST CONDITIONS	MIN	MAX	UNIT
V_{OH}	High-level output voltage	DX	$I_H = -3.2\text{ mA}$	2.4		V
V_{OL}	Low-level output voltage	DX	$I_L = 3.2\text{ mA}$		0.4	V
		TSX	$I_L = 3.2\text{ mA}$, Drain open		0.4	
I_{IH}	High-level input current		$V_I = V_{IH}$ to V_{CC}	± 10		μA
I_{IL}	Low-level input current	All digital inputs	$V_I = \text{GND}$ to V_{IL}	± 10		μA
I_{OZ}	Output current in high-impedance state	DX	$V_O = \text{GND}$ to V_{CC}	± 10		μA

analog interface with transmit amplifier input

PARAMETER		TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
$V_{ICR}^\ddagger$	Common-mode input voltage range				± 2.5	V
I_I	Input current	VFXI+ or VFXI –	$V_I = -2.5\text{ V}$ to 2.5 V		± 200	nA
r_i	Input resistance	VFXI+ or VFXI –	$V_I = -2.5\text{ V}$ to 2.5 V	10		M Ω
A_V	Open-loop voltage amplification	VFXI+ to GSX		5000		
B_I	Unity-gain bandwidth	GSX		1	2	MHz
V_{IO}	Input offset voltage	VFXI+ or VFXI –			± 20	mV
CMRR	Common-mode rejection ratio			60		dB
K_{SVR}	Supply-voltage rejection ratio			60		dB

[†] All typical values are at $V_{CC} = 5\text{ V}$, $V_{BB} = -5\text{ V}$, and $T_A = 25^\circ\text{C}$.

[‡] Measured with CMRR > 60 dB.

analog interface with receive amplifier output

PARAMETER		TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Receive output drive voltage		$R_L = 10\text{ k}\Omega$			± 2.5	V
Output resistance	VFRO			1	3	Ω
Load resistance		$VFRO = \pm 2.5\text{ V}$	600			Ω
Load capacitance	VFRO to GND				500	pF
Output dc offset voltage	VFRO to GND				± 200	mV

[†] All typical values are at $V_{CC} = 5\text{ V}$, $V_{BB} = -5\text{ V}$, and $T_A = 25^\circ\text{C}$.

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operating characteristics, over operating free-air temperature range, $V_{CC} = 5\text{ V} \pm 5\%$, $V_{BB} = -5\text{ V} \pm 5\%$, GND at 0 V, $V_I = 1.2276\text{ V}$, $f = 1.02\text{ kHz}$, transmit input amplifier connected for unity gain, noninverting, in A-law and μ -law modes, (unless otherwise noted)

filter gains and tracking errors

PARAMETER		TEST CONDITIONS		MIN	TYP [†]	MAX	UNIT
Maximum peak transmit overload level	μ-law	3.17 dBm0		2.501			V
	A-law	3.14 dBm0		2.492			
Transmit filter gain, absolute [‡] (at 0 dBm0)		T _A = 25°C		− 0.15		0.15	dB
Transmit filter gain, relative to absolute [‡]		f = 16 Hz				−40	dB
		f = 50 Hz				−30	
		f = 60 Hz				−26	
		f = 200 Hz		−1.8		−0.1	
		f = 300 Hz to 3000 Hz		−0.15		0.15	
		f = 3300 Hz		−0.35		0.05	
		f = 3400 Hz		−0.8		0	
		f = 4000 Hz				−14	
		f ≥ 4600 Hz (measure response from 0 Hz to 4000 Hz)				−32	
Absolute [‡] transmit gain variation with temperature and supply voltage relative to absolute transmit gain				−0.1		0.1	dB
Transmit gain tracking error with level		Sinusoidal test method, Reference level = −10 dBm0	3 dBm0 ≥ input level ≥ −40 dBm0			±0.2	dB
			−40 dBm0 > input level ≥ −50 dBm0			±0.4	
			−50 dBm0 > input level ≥ −55 dBm0			±0.8	
Receive filter gain, absolute [‡] (at 0 dBm0)		Input is digital code sequence for 0-dBm0 signal, T _A = 25°C		−0.15		0.15	dB
Receive filter gain, relative to absolute [‡]	f = 0 Hz to 3000 Hz,		T _A = 25°C	−0.15		0.15	dB
	f = 3300 Hz			−0.35		0.05	
	f = 3400 Hz			−0.8		0	
	f = 4000 Hz					−14	
Absolute [‡] receive gain variation with temperature and supply voltage		T _A = full range, See Note 3		−0.1		0.1	dB
Receive gain tracking error with level		Sinusoidal test method; reference input PCM code corresponds to an ideally encoded −10 dBm0 signal	3 dBm0 ≥ input level ≥ −40 dBm0			±0.2	dB
			−40 dBm0 > input level ≥ −50 dBm0			±0.4	
			−50 dBm0 > input level ≥ −55 dBm0			±0.8	
Transmit and receive gain tracking error with level (A-law, CCITT G 712)		Pseudo-noise test method; reference input PCM code corresponds to an ideally encoded −10 dBm0 signal	3 dBm0 ≥ input level ≥ −40 dBm0			±0.25	dB
			−40 dBm0 > input level ≥ −50 dBm0			±0.3	
			−50 dBm0 > input level ≥ −55 dBm0			±0.45	

[†] All typical values are at $V_{CC} = 5\text{ V}$, $V_{BB} = -5\text{ V}$, and $T_A = 25^\circ\text{C}$.

[‡] Absolute rms signal levels are defined as follows: $V_I = 1.2276\text{ V} = 0\text{ dBm0} = 4\text{ dBm}$ at $f = 1.02\text{ kHz}$ with $R_L = 600\ \Omega$.

NOTE 3: Full range for the TP3056B is 0°C to 70°C .



operating characteristics, over operating free-air temperature range, $V_{CC} = 5\text{ V} \pm 5\%$, $V_{BB} = -5\text{ V} \pm 5\%$, GND at 0 V, $V_I = 1.2276\text{ V}$, $f = 1.02\text{ kHz}$, transmit input amplifier connected for unity gain, noninverting, in A-law and μ -law modes, (unless otherwise noted) (continued)

envelope delay distortion with frequency

PARAMETER	TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Transmit delay, absolute (at 0 dBm0)	$f = 1600\text{ Hz}$		290	315	μs
Transmit delay, relative to absolute [‡]	$f = 500\text{ Hz to }600\text{ Hz}$		195	220	μs
	$f = 600\text{ Hz to }800\text{ Hz}$		120	145	
	$f = 800\text{ Hz to }1000\text{ Hz}$		50	75	
	$f = 1000\text{ Hz to }1600\text{ Hz}$		20	40	
	$f = 1600\text{ Hz to }2600\text{ Hz}$		55	75	
	$f = 2600\text{ Hz to }2800\text{ Hz}$		80	105	
	$f = 2800\text{ Hz to }3000\text{ Hz}$		130	155	
Receive delay, absolute (at 0 dBm0)	$f = 1600\text{ Hz}$		180	200	μs
Receive delay, relative to absolute [‡]	$f = 500\text{ Hz to }1000\text{ Hz}$	-40	-25		μs
	$f = 1000\text{ Hz to }1600\text{ Hz}$	-30	-20		
	$f = 1600\text{ Hz to }2600\text{ Hz}$		70	90	
	$f = 2600\text{ Hz to }2800\text{ Hz}$		100	125	
	$f = 2800\text{ Hz to }3000\text{ Hz}$		140	175	

[†] All typical values are at $V_{CC} = 5\text{ V}$, $V_{BB} = -5\text{ V}$, and $T_A = 25^\circ\text{C}$.

[‡] Absolute rms signal levels are defined as follows: $V_I = 1.2276\text{ V} = 0\text{ dBm0} = 4\text{ dBm}$ at $f = 1.02\text{ kHz}$ with $R_L = 600\ \Omega$.

noise

PARAMETER		TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Transmit noise, C-message weighted	μ -law	$V_{FXI} = 0\text{ V}$		9	14	dBrnC0
Transmit noise, psophometric weighted (see Note 4)	A-law	$V_{FXI} = 0\text{ V}$		-78	-75	dBm0p
Receive noise, C-message weighted	μ -law	PCM code equals alternating positive and negative zero.		2	4	dBrnC0
Receive noise, psophometric weighted	A-law	PCM code equals positive zero.		-86	-83	dBm0p
Noise, single frequency		$V_{FXI+} = 0\text{ V}$, $f = 0\text{ kHz to }100\text{ kHz}$, Loop-around measurement			-53	dBm0

[†] All typical values are at $V_{CC} = 5\text{ V}$, $V_{BB} = -5\text{ V}$, and $T_A = 25^\circ\text{C}$.

NOTE 4: Measured by extrapolation from the distortion test result. This parameter is achieved through use of patented circuitry and is not recommended for applications in which the composite signals on the transmit side are below -55 dBm0.

crosstalk

PARAMETER	TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Crosstalk, transmit to receive	$f = 300\text{ Hz to }3000\text{ Hz}$, DR at steady PCM code		-90	-75	dB
Crosstalk, receive to transmit (see Note 5)	$V_{FXI} = 0\text{ V}$, $f = 300\text{ Hz to }3000\text{ Hz}$		-90	-75	dB

[†] All typical values are at $V_{CC} = 5\text{ V}$, $V_{BB} = -5\text{ V}$, and $T_A = 25^\circ\text{C}$.

NOTE 5: Receive-to-transmit crosstalk is measured with a -50 dBm0 activation signal applied at V_{FXI+} .

power amplifiers

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
Maximum 0 dBm0 rms level for better than $\pm 0.1\text{ dB}$ linearity over the range if -10 dBm0 to 3 dBm0	Balanced load, R_L , connected between V_{FRO} and Gnd	$R_L = 600\ \Omega$	1.65	V_{rms}
		$R_L = 1200\ \Omega$	1.75	
		$R_L = 30\text{ k}\Omega$	2	
Signal/distortion	$R_L = 600\ \Omega$		50	dB

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operating characteristics, over operating free-air temperature range, $V_{CC} = 5\text{ V} \pm 5\%$, $V_{BB} = -5\text{ V} \pm 5\%$, GND at 0 V, $V_I = 1.2276\text{ V}$, $f = 1.02\text{ kHz}$, transmit input amplifier connected for unity gain, noninverting, in A-law and μ -law modes, (unless otherwise noted) (continued)

power supply rejection

PARAMETER	TEST CONDITIONS		MIN	MAX	UNIT
Positive power-supply rejection, transmit	$V_{CC} = 5\text{ V} + 100\text{ mVrms}$, $V_{FXI+} = -50\text{ dBm0}$	$f = 0\text{ Hz to }4\text{ kHz}$	A-law	38	dB
			μ -law	38	dB [†]
		$f = 4\text{ kHz to }50\text{ kHz}$		40	dB
Negative power-supply rejection, transmit	$V_{BB} = -5\text{ V} + 100\text{ mVrms}$, $V_{FXI+} = -50\text{ dBm0}$	$f = 0\text{ Hz to }4\text{ kHz}$	A-law	35	dB
			μ -law	35	dB [†]
		$f = 4\text{ kHz to }50\text{ kHz}$		40	dB
Positive power-supply rejection, receive	PCM code equals positive zero, $V_{CC} = 5\text{ V} + 100\text{ mVrms}$	$f = 0\text{ Hz to }4\text{ kHz}$	A-law	40	dB
			μ -law	40	dB [†]
		$f = 4\text{ kHz to }50\text{ kHz}$		40	dB
Negative power-supply rejection, receive	PCM code equals positive zero, $V_{BB} = -5\text{ V} + 100\text{ mVrms}$	$f = 0\text{ Hz to }4\text{ kHz}$	A-law	38	dB
			μ -law	38	dB [†]
		$f = 4\text{ kHz to }50\text{ kHz}$		40	dB
Spurious out-of-band signals at the channel output (VFRO)	0 dBm0, 300-Hz to 3400-Hz input applied to DR (measure individual image signals at VFRO)			-30	dB
	$f = 4600\text{ Hz to }7600\text{ Hz}$			-33	dB
	$f = 7600\text{ Hz to }8400\text{ Hz}$			-40	
	$f = 8400\text{ Hz to }100\text{ kHz}$			-40	

[†] The unit dB[†] applies to C-message weighting.

operating characteristics, over operating free-air temperature range, $V_{CC} = 5\text{ V} \pm 5\%$, $V_{BB} = -5\text{ V} \pm 5\%$, GND at 0 V, $V_I = 1.2276\text{ V}$, $f = 1.02\text{ kHz}$, transmit input amplifier connected for unity gain, noninverting, in A-law and μ -law modes, (unless otherwise noted) (continued)

distortion

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
Signal-to-distortion ratio, transmit or receive half-channel [‡]	Level = 3 dBm0	33		dBC [†]
	Level = 0 dBm0 to -30 dBm0	36		
	Level = -40 dBm0	Transmit	29	
		Receive	30	
	Level = -55 dBm0	Transmit	14	
		Receive	15	
Single-frequency distortion products, transmit			-46	dB
Single-frequency distortion products, receive			-46	dB
Intermodulation distortion	Loop-around measurement, VFXI+ = -4 dBm0 to -21 dBm0, Two frequencies in the range of 300 Hz to 3400 Hz		-41	dB
Signal-to-distortion ratio, transmit half-channel (A-law) (CCITT G.714) [§]	Level = -3 dBm0	33		dB
	Level = -6 dBm0 to -27 dBm0	36		
	Level = -34 dBm0	33.5		
	Level = -40 dBm0	28.5		
	Level = -55 dBm0	13.5		
Signal-to-distortion ratio, receive half-channel (A-law) (CCITT G.714) [§]	Level = -3 dBm0	33		dB
	Level = -6 dBm0 to -27 dBm0	36		
	Level = -34 dBm0	34.2		
	Level = -40 dBm0	30		
	Level = -55 dBm0	15		

[†] The unit dBC applies to C-message weighting.

[‡] Sinusoidal test method (see Note 6)

[§] Pseudo-noise test method

NOTE 6: μ -law measurements are made using a C-message weighted filter, and A-law measurements are made using a psophometric weighted filter.

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timing requirements over recommended ranges of operating conditions (see Figures 1 and 2)

			MIN	NOM	MAX	UNIT
$f_{\text{clock(M)}}$	Frequency of master clock	MCLK		2.048		MHz
$f_{\text{clock(B)}}$	Frequency of bit clock, transmit	BCLK	64		2048	kHz
t_{w1}	Pulse duration, MCLK high		160			ns
t_{w2}	Pulse duration, MCLK low		160			ns
t_{r1}	Rise time of master clock (20% to 80%)	MCLK			50	ns
t_{f1}	Fall time of master clock (80% to 20%)				50	ns
t_{r2}	Rise time of bit clock (20% to 80%), transmit	BCLK			50	ns
t_{f2}	Fall time of bit clock (80% to 20%), transmit				50	ns
t_{su1}	Setup time, BCLK high (and FSX in long-frame sync mode) before MCLK ↓ (first bit clock after the leading edge of FSX)		100			ns
t_{w3}	Pulse duration, BCLK high, $V_{IH} = 2.2$ V		160			ns
t_{w4}	Pulse duration, BCLK low, $V_{IL} = 0.6$ V		160			ns
t_{h1}	Hold time, FSX or FSR low after BCLK low (long frame only)		0			ns
t_{h2}	Hold time, BCLK high after FSX or FSR ↑ (short frame only)		0			ns
t_{su2}	Setup time, FSX or FSR high before BCLK ↓ (long frame only)		80			ns
t_{su3}	Setup time, DR valid before BCLK ↓		50			ns
t_{h3}	Hold time, DR valid after BCLK ↓		50			ns
t_{su4}	Setup time, FSX or FSR high before BCLK ↓, short-frame sync pulse (1 or 2 bit-clock periods long) (see Note 7)		50			ns
t_{h4}	Hold time, FSX or FSR high after BCLK ↓, short-frame sync pulse (1 or 2 bit-clock periods long) (see Note 7)		100			ns
t_{h5}	Hold time, FSX or FSR high after BCLK ↓, long-frame sync pulse (from 3 to 8 bit-clock periods long)		100			ns
t_{w5}	Minimum pulse duration of FSX or FSR (frame sync pulse — low level), 64-kbps operating mode		160			ns

NOTE 7: For short-frame sync timing, FSR and FSX must go high while their respective bit clocks are high.

switching characteristics over recommended ranges of operating conditions (see Figures 1 and 2)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
t _{d1}	Delay time, BCLK high to data valid at DX	Load = 150 pF plus 2 LSTTL loads [†]	0	140	ns
t _{d2}	Delay time, BCLK high to $\overline{\text{TSX}}$ low	Load = 150 pF plus 2 LSTTL loads [†]		140	ns
t _{d3}	Delay time, BCLK (or 8 clock FSX in long frame only) low to data output (DX) disabled		50	165	ns
t _{d4}	Delay time, FSX or BCLK high to data valid at DX (long frame only)	C _L = 0 pF to 150 pF	20	165	ns

[†] Nominal input value for an LSTTL load is 18 kΩ.

PARAMETER MEASUREMENT INFORMATION

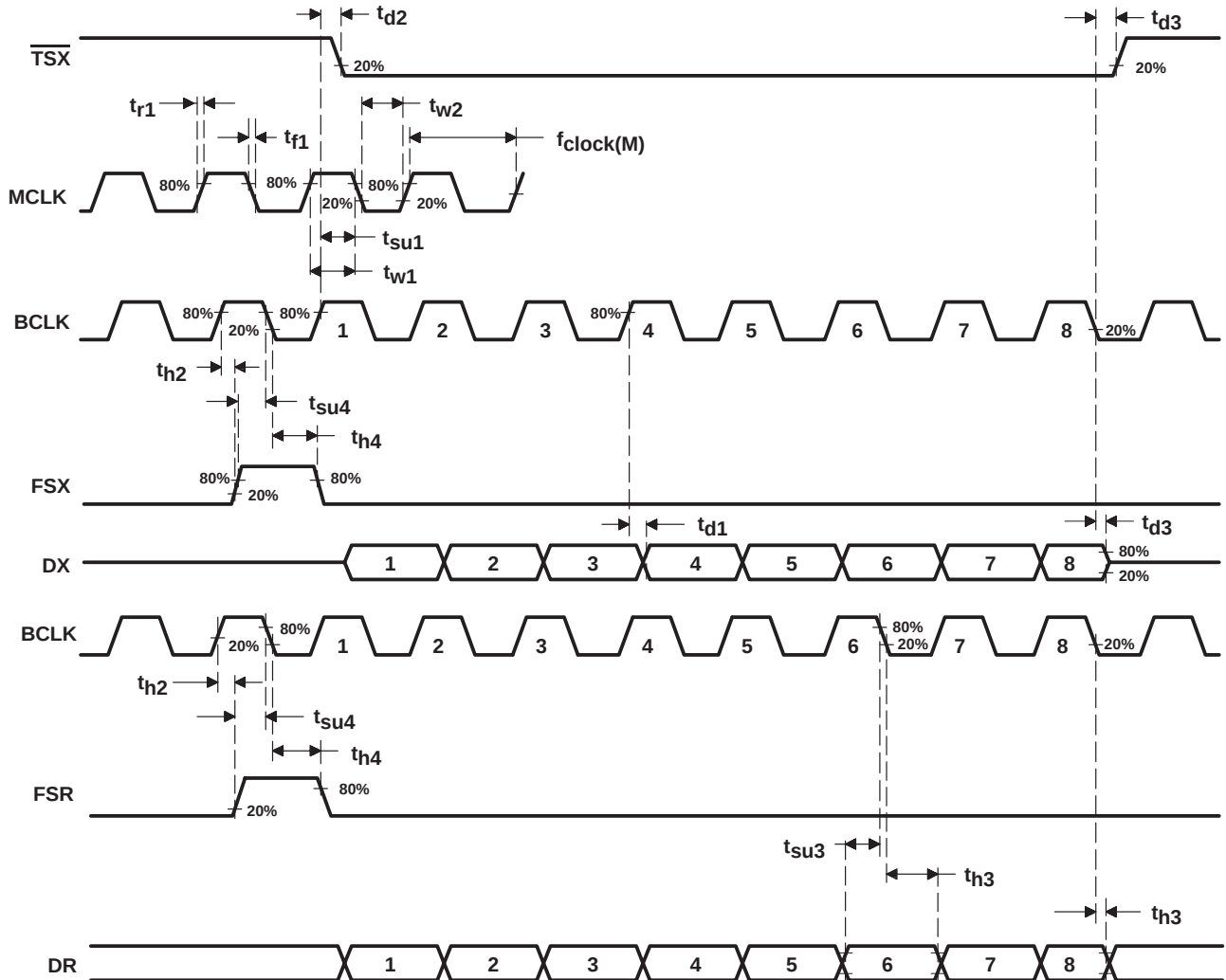


Figure 1. Short Frame Sync Timing

PARAMETER MEASUREMENT INFORMATION

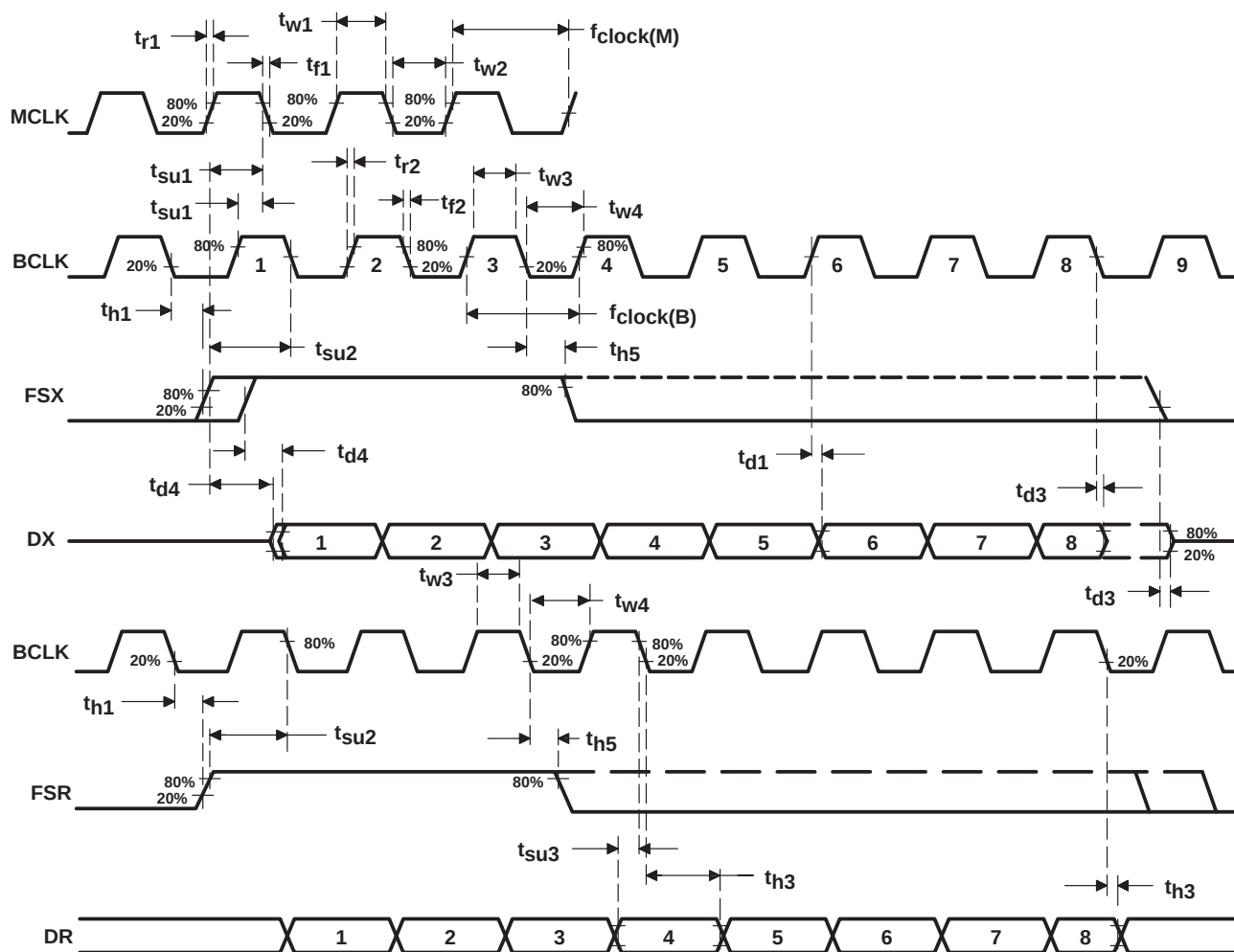


Figure 2. Long Frame Sync Timing

PRINCIPLES OF OPERATION

system reliability and design considerations

TP3056B system reliability and design considerations are described in the following paragraphs.

latch-up

Latch-up is possible in all CMOS devices. It is caused by the firing of a parasitic SCR that is present due to the inherent nature of CMOS. When a latch-up occurs, the device draws excessive amounts of current and will continue to draw heavy current until power is removed. Latch-up can result in permanent damage to the device if supply current to the device is not limited.

Even though the TP3056B is heavily protected against latch-up, it is still possible to cause latch-up under certain conditions in which excess current is forced into or out of one or more terminals. Latch-up can occur when the positive supply voltage drops momentarily below ground, when the negative supply voltage rises momentarily above ground, or possibly if a signal is applied to a terminal after power has been applied but before the ground is connected. This can happen if the device is hot-inserted into a card with the power applied, or if the device is mounted on a card that has an edge connector and the card is hot-inserted into a system with the power on.

To help ensure that latch-up does not occur, it is considered good design practice to connect a reverse-biased Schottky diode with a forward voltage drop of less than or equal to 0.4 V (1N5711 or equivalent) between the power supply and GND (see Figure 3). If it is possible that a TP3056B-equipped card that has an edge connector could be hot-inserted into a powered-up system, it is also important to ensure that the ground edge connector traces are longer than the power and signal traces so that the card ground is always the first to make contact.

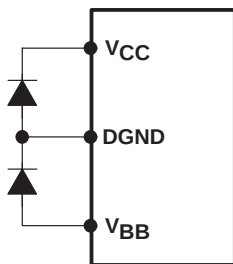


Figure 3. Latch-Up Protection Diode Connection

PRINCIPLES OF OPERATION

system reliability and design considerations (continued)

device power-up sequence

Latch-up also can occur if a signal source is connected without the device being properly grounded. A signal applied to one terminal could then find a ground through another signal terminal on the device. To ensure proper operation of the device and as a safeguard against this sort of latch-up, it is recommended that the following power-up sequence always be used:

1. Ensure that no signals are applied to the device before the power-up sequence is complete.
2. Connect GND.
3. Apply V_{BB} (most negative voltage).
4. Apply V_{CC} (most positive voltage).
5. Force a power down condition in the device.
6. Connect clocks.
7. Release the power down condition.
8. Apply FS synchronization pulses.
9. Apply the signal inputs.

When powering down the device, this procedure should be followed in the reverse order.

internal sequencing

Power-on reset circuitry initializes the TP3056B device when power is first applied, placing it in the power-down mode. The DX and VFRO outputs go into the high-impedance state and all nonessential circuitry is disabled. A low level applied to the PDN terminal powers up the device and activates all internal circuits. The 3-state PCM data output, DX, remains in the high-impedance state until the arrival of the second FSX pulse.

general operation

A 2.048-MHz clock signal applied to MCLK serves as the master clock for both the receive and the transmit directions. BCLK must have a bit clock signal applied to it, which then serves as the bit clock for both the receive and the transmit directions. BCLK can be in the range from 64 kHz to 2.048 MHz, but must be synchronous with MCLK.

The encoding cycle begins with each FSX pulse, and the PCM data from the previous cycle is shifted out of the enabled DX output on the rising edge of BCLK. After eight bit-clock periods, the 3-state DX output is returned to the high-impedance state. With an FSR pulse, PCM data is latched in via DR on the falling edge of BCLK. FSX and FSR must be synchronous with MCLK.

PRINCIPLES OF OPERATION

short-frame sync operation

The device can operate with either a short-frame sync pulse or a long-frame sync pulse. On power up, the device automatically goes into the short-frame mode where both FSX and FSR must be one bit-clock period long with timing relationships specified in Figure 1. With FSX high during a falling edge of BCLK, the next rising edge of BCLK enables the 3-state output buffer, outputting the sign bit at DX. The remaining seven bits are shifted out on the following seven rising edges, with the next falling edge disabling DX. With FSR high during a falling edge of BCLK, the next falling edge of BCLK latches in the sign bit. The following seven falling edges latch in the seven remaining bits.

long-frame sync operation

Both FSX and FSR must be three or more bit-clock periods long to use the long-frame sync mode with timing relationships as shown in Figure 2. Using the transmit frame sync (FSX), the device determines whether a short- or long-frame sync pulse is being used. For 64-kHz operation, the frame-sync pulse must be kept low for a minimum of 160 ns. The rising edge of FSX or BCLK, whichever occurs later, enables the 3-state output buffer, outputting the sign bit at DX. The next seven rising edges of BCLK shift out the remaining seven bits. The falling edge of BCLK following the eighth rising edge, or FSX going low, whichever occurs later, disables DX. A rising edge on FSR, the receive-frame sync pulse, causes the PCM data at DR to be latched in on the next eight falling edges of BCLK.

transmit section

The transmit section consists of an input amplifier, filters, and an encoding ADC. The input is an operational amplifier with provision for gain adjustment using two external resistors. The low-noise and wide-bandwidth characteristics of these devices provide gains in excess of 20 dB across the audio passband. The operational amplifier drives a unity-gain filter consisting of an RC active prefilter followed by an eighth-order switched-capacitor band-pass filter clocked at 256 kHz. The output of this filter is routed to the encoder sample-and-hold circuit. The ADC is a compressing type and converts the analog signal to PCM data in accordance with μ -law or A-law coding conventions, as selected. A precision voltage reference provides a nominal input overload voltage of 2.5 V peak.

The sampling of the filter output is controlled by the FSX frame-sync pulse; then the successive-approximation encoding cycle begins. The resulting 8-bit code is loaded into a buffer and shifted out through DX at the next FSX pulse. The total encoding delay is approximately 290 μ s. Any offset voltage due to the filters or comparator is cancelled by sign-bit integration.

receive section

The receive section is unity gain and consists of an expanding DAC, filters, and a power amplifier. Decoding is μ -law or A-law (as selected by the ASEL terminal), and the decoded analog output signal is routed to the input of a fifth-order switched-capacitor low-pass filter. This filter is clocked at 256 kHz and corrects for the $(\sin x)/x$ attenuation caused by the 8-kHz sample/hold of the DAC. Next is a second-order RC active post-filter/power amplifier capable of driving an external 600- Ω load.

When FSR goes high, the data at DR is stepped in on the falling edge of the next eight BCLK clocks. At the end of the decoder time slot, the decoding cycle begins and 10 μ s later, the decoder DAC output is updated. The decoder delay is about 10 μ s (decoder update) plus 110 μ s (filter delay) plus 62.5 μ s (1/2 frame), or a total of approximately 180 μ s.

TP3056B

MONOLITHIC SERIAL INTERFACE

COMBINED PCM CODEC AND FILTER

SLWS072A – MAY 1998 – REVISED AUGUST 1998

APPLICATION INFORMATION

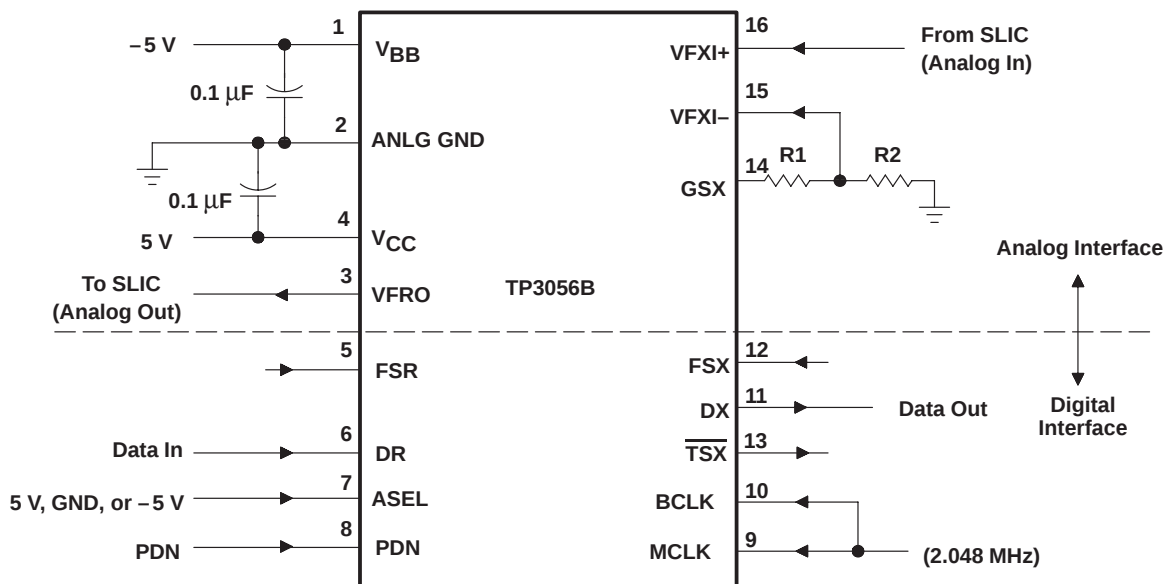
power supplies

While the terminals of the TP3056B device is well protected against electrical misuse, it is recommended that the standard CMOS practice be followed, ensuring that ground is connected to the device before any other connections are made. In applications where the printed-circuit board can be plugged into a hot socket with power and clocks already present, an extra long ground pin in the connector should be used.

All ground connections to each device should meet at a common point as close as possible to the device ANLG GND terminal. This minimizes the interaction of ground return currents flowing through a common bus impedance. V_{CC} and V_{BB} supplies should be decoupled by connecting 0.1- μ F decoupling capacitors to this common point. These bypass capacitors must be connected as close as possible to the device V_{CC} and V_{BB} terminals.

For best performance, the ground point of each codec/filter on a card should be connected to a common card ground in star formation rather than via a ground bus. This common ground point should be decoupled to V_{CC} and V_{BB} with 10- μ F capacitors.

Figure 4 shows a typical TP3056B application.



NOTE A: Transmit gain = $20 \log \left(\frac{R1 + R2}{R2} \right)$, $(R1 + R2) \geq 10 \text{ k}\Omega$

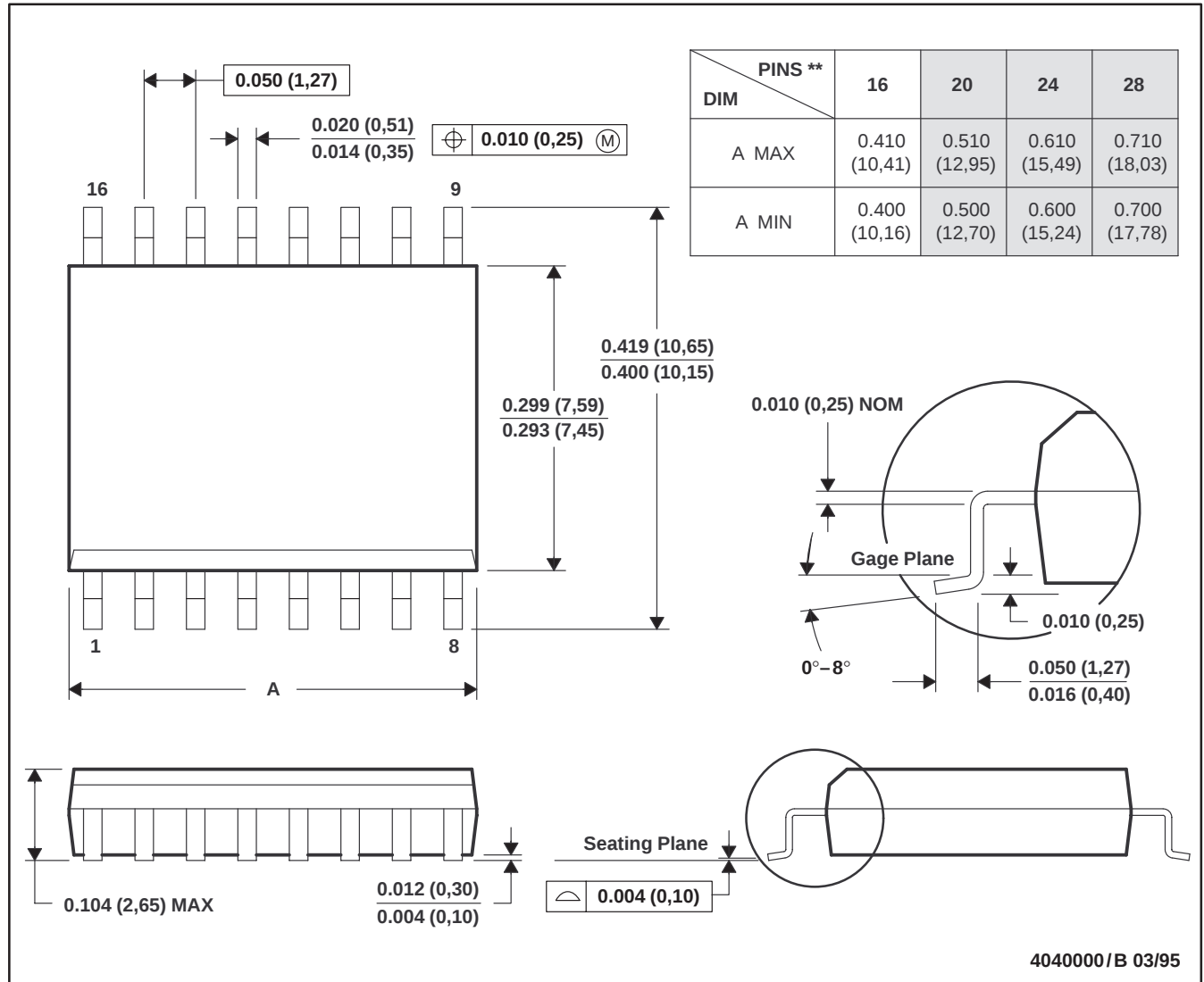
Figure 4. Typical Synchronous Application

MECHANICAL DATA

DW (R-PDSO-G)**

PLASTIC SMALL-OUTLINE PACKAGE

16 PIN SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).
 B. This drawing is subject to change without notice.
 C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
 D. Falls within JEDEC MS-013

TP3056B
MONOLITHIC SERIAL INTERFACE
COMBINED PCM CODEC AND FILTER

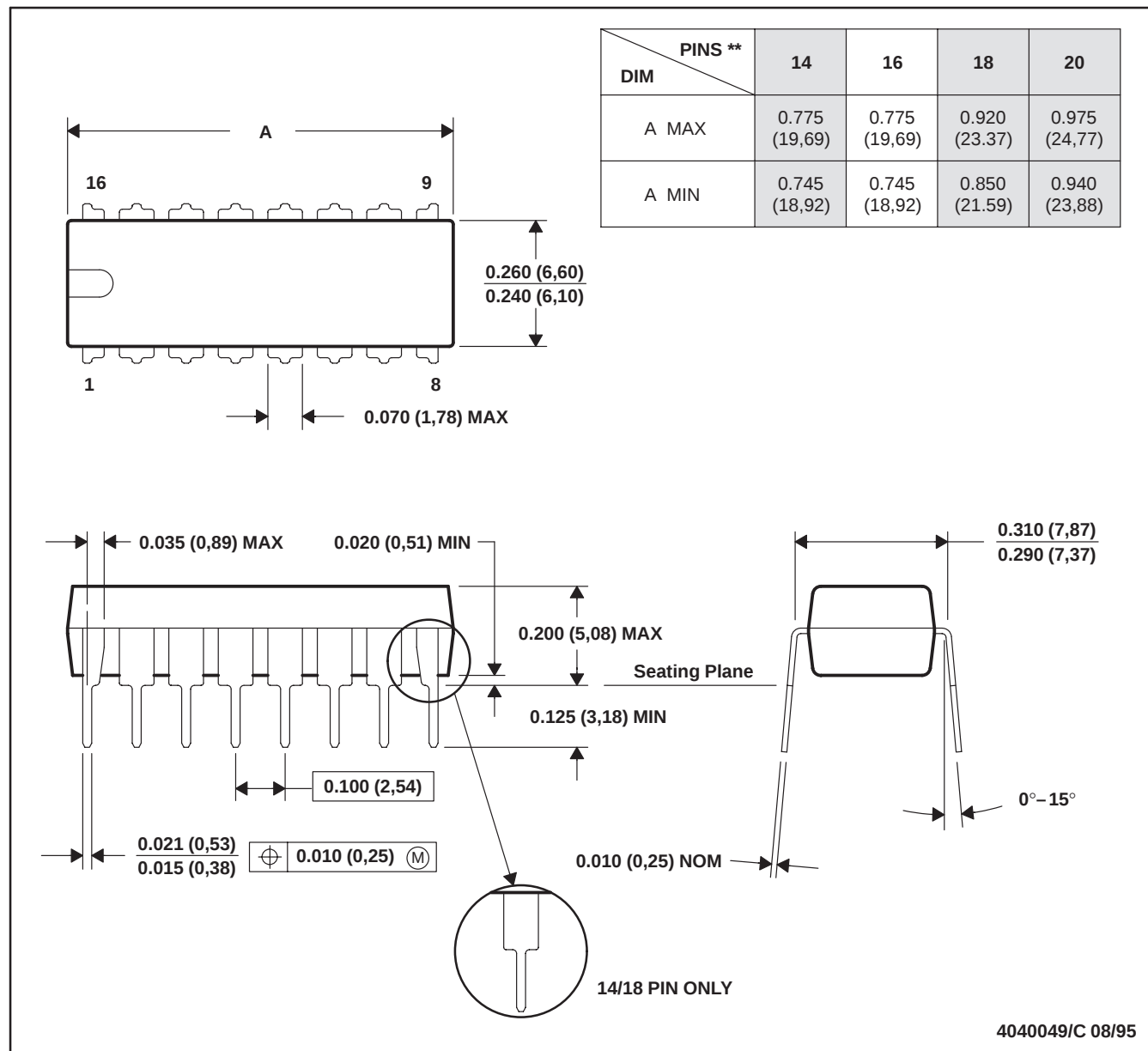
SLWS072A – MAY 1998 – REVISED AUGUST 1998

MECHANICAL DATA

N (R-PDIP-T)**

PLASTIC DUAL-IN-LINE PACKAGE

16 PIN SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).
 B. This drawing is subject to change without notice.
 C. Falls within JEDEC MS-001 (20 pin package is shorter than MS-001.)

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